**PO2EBL\_ELECTRIC BLENDER**

**CYRS DOCUMENT**

**Version 2.4**

**Proposed**

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| 02/20/2020 | 2.4 | Proposed | Mohamed Ibrahem |

# Document Status:

# Revision History

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| **Date** | **Version** | **Status** | **Description** | **Author** |
| 01/22/2020 | 1.1 | Draft | Initial Draft, specifying Introduction, system overview and document outline. | May Alaa El-din |
| 01/23/2020 | 1.2 | Draft | Update the draft, requirements table | Mohamed Ibrahem |
| 01/25/2020 | 1.3 | Proposed | Reviewed Document structure and updated Document status to Proposed | May Alaa El-din |
| 01/31/2020 | 1.4 | Proposed | Update the requirement according the review (safe monitoring, monitoring speed, add reference table). | Mohamed Ibrahem |
| 02/01/2020 | 1.5 | Proposed | Update the reference table, requirement table | Mohamed Ibrahem |
| 02/03/2020 | 1.6 | Proposed | Update the CYRS document versioning | Mohamed Ibrahem |
| 02/06/2020 | 1.7 | Proposed | Update the CYRS requirements according to SIQ sheet (Remove REQ\_PO2EBL\_CYRS\_03) | Mohamed Ibrahem |
| 02/06/2020 | 1.8 | Proposed | Review CYRS and update Current document status table | Ali Samir |
| 02/07/2020 | 1.9 | Proposed | Update the date format in page 2 , modify REQ\_P02EBL\_CYRS\_02 and remove Hardware section | Mohamed Ibrahem |
| 02/08/2020 | 2 | Proposed | Update the CYRS documents versioning | Mohamed Ibrahem |
| 02/08/2020 | 2.1 | Proposed | Update the Date format | Mohamed Ibrahem |
| 02/11/2020 | 2.2 | Proposed | Update the date format Add Block diagram and Add Control inputs with outputs REQ\_PO2EBL\_CYRS\_04\_V1.0 | Mohamed Ibrahem |
| 02/11/2020 | 2.3 | Released | Changed the Document status to released | May Alaa |
| 02/20/2020 | 2.4 | Proposed | Update the block diagram, adding table figures,2 requirement REQ\_PO2EBL\_CYRS\_04\_V1.0  REQ\_PO2EBL\_CYRS\_05\_V1.0  rename requirement  REQ\_PO2EBL\_CYRS\_03\_V1.4 | Mohamed Ibrahem |
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# **1 Introduction**

This section introduces the customer requirements specification (CYRS) for the KENOVO Electric Blender.

## 1.1 Specification Definition

This specification documents the system-level requirements for the Electric Blender.

## 1.2 Specification Objectives

The objectives of this specification are to:

* Provide a system overview of the Electric Blender including definition, goals, objectives, context, and major capabilities.
* To formally specify its associated:
* Functional requirements.
* Data requirements.
* Quality requirements.
* Constraints.

# 2 System Overview:

## 2.1 Definition:

The Electric Blender System is an appliance created by KENOVO. The electric blender system has 3 speeds that can be configured by the user with high safety to avoid system failure caused by unexpected voltage peaks.

## 2.2 Objective:

The objective of the Electric Blender System is to provide the user with a high quality home appliance with high-speed configurability as well as safety monitoring.

## 2.3 Block Diagram

Figure Block Diagram

# 3 Functional Requirements:

|  |  |  |
| --- | --- | --- |
| Feature | Requirement ID | Description |
| 3.1 Speed Levels | REQ\_PO2EBL\_CYRS\_01\_V1.3 | The system has four status three speed levels and the Off status. **#imp SW** |
| 3.2 Speed Controls | REQ\_PO2EBL\_CYRS\_02\_V1.6 | the blender shall operate between 3 different speeds (Speed1 → Speed 2 → Speed 3) triggered by a button press after the fourth press it returns back to its initial state (off).  **#imp SW** |
| 3.3 Speed indication | REQ\_PO2EBL\_CYRS\_03\_V1.4 | The system shall monitor the blender speed and turns on led and its light intensity correspond to a specific speed of the blender. **#imp SW** |
| 3.4 DC motor Control | REQ\_PO2EBL\_CYRS\_04\_V1.0 | The DC motor can be controlled using a transistor that act as an isolation level between the controller and the motor. When the system needs to switch on the motor the controller shall give an enable signal to the transistor that enable the motor to operate.  **#imp SW** |
| 3.5 Safety monitor | REQ\_PO2EBL\_CYRS\_05\_V1.0 | The system shall monitor the voltage level that entered to the system by voltage level sensor. The reading of the sensor can be digitalize using analog to digital convertor.  If the voltage level is not the optimum level, which the system can operate safely, the system shall switched off.  **#imp SW** |

# 4 Reference table:

|  |  |  |  |
| --- | --- | --- | --- |
| **ID** | **Version** | **Document** | **Status** |
| 1 | 1.0 | Electric Blender customer requirement | Released |
| 2 | - | SIQ | - |